## ECE 174 Midterm - Fall 2010 — Solutions

1. (35 pts) Let the $m \times n$ matrix $A$ represent a linear mapping between two complex Hilbert spaces $\mathcal{X}$ and $\mathcal{Y}$ with inner-product weighting matrices given by $\Omega$ and $W$ respectively. (You can assume that all vectors are represented canonically.)
(a) Derive the form of the adjoint of $A$, from the fundamental definition of the adjoint.

All of the solutions to Problem 1, except the last part, can be found in the homework solutions. They are straightforward. For example the first solution is:

$$
\begin{aligned}
\langle y, A x\rangle & =y^{H} W A x \\
& =y^{H} W A \Omega^{-1} \Omega x \\
& =\left(\Omega^{-1} A^{H} W y\right)^{H} \Omega x \\
& =\left\langle\left(\Omega^{-1} A^{H} W\right) y, x\right\rangle \\
& \Longrightarrow A^{*}=\Omega^{-1} A^{H} W
\end{aligned}
$$

(b) Show the relationships between the range spaces and nullspaces of $A$ and its adjoint. (Just show. You do not have to derive these relationships.) Draw a simple picture to illustrate these relationships.

The relationships are:

$$
\mathbb{C}^{n}=\mathcal{X}=\mathcal{N}(A)^{\perp} \oplus \mathcal{N}(A)=\mathcal{R}\left(A^{*}\right) \oplus \mathcal{N}(A)
$$

and

$$
\mathbb{C}^{m}=\mathcal{Y}=\mathcal{R}(A) \oplus \mathcal{R}(A)^{\perp}=\mathcal{R}(A) \oplus \mathcal{N}\left(A^{*}\right)
$$

You should be able to draw simple pictures that capture these relationships (in particular the orthogonality relationships that exist between the complementary subspaces).
(c) Consider the inverse problem $y=A x$. i) Derive the algebraic condition for a leastsquares solution to exist. ii) Derive the algebraic condition for a least-squares solution to be the minimum norm least-squares solution.

See the homework solutions.
(d) Derive explicit expressions for the pseudoinverse of $A$ that are possible if it is known that $A$ has full rank. Place them in their simplest possible form. (Hint: There are two different conditions that you have to consider.)

See the homework solutions.
(e) Construct the pseudoinverse of $A$ for $\Omega, W$, and $A$ given by

$$
\Omega=\left(\begin{array}{ccc}
4.80 & 1+2 j & 0.01+0.02 j \\
1-2 j & 9.76 & 2-j \\
0.01-0.02 j & 2+j & 129.21
\end{array}\right), \quad W=\left(\begin{array}{cccc}
721.839 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{array}\right), \quad A=\left(\begin{array}{lll}
0 & 0 & 0 \\
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & 1
\end{array}\right),
$$

where $j=\sqrt{-1}$. Give the pseudoinverse in its simplest possible form.
Because $A$ has full column rank, the weighting matrix $\Omega$ will not show up in the pseudoinverse

$$
A^{+}=\left(A^{*} A\right)^{-1} A^{*}=\left(A^{H} W A\right)^{-1} A^{H} W=\left(A^{T} W A\right)^{-1} A^{T} W .
$$

Further, it is straightforward to show that $W A=A$ (equivalently that $A^{T} W=$ $A^{T}$ ), so that $A^{+}=\left(A^{T} A\right)^{-1} A^{T}$. Finally, it is straightforward to show that $A^{T} A=I$, yielding the answer $A^{+}=A^{T}$.
2. (40pts) Using radar, $m$ noisy measurements, $y_{i}, i=1, \cdots, m$, are made of the unknown constant speed (not velocity) of an unidentified aircraft. Determine the least squares estimate of the speed from the sensor data as follows.
(a) Set up an inverse problem of the form $y=A x$. To do so, Completely specify appropriate input and output Hilbert spaces, showing the definitions of the standard inner-products and clearly specifying the elements and dimensions of the matrix $A$.

See below.
(b) i) Give the rank of $A$ and the dimensions of the four fundamental subspaces. ii) Is the problem ill-posed? Explain and justify your answers.

Letting $x \in \mathcal{X}=\mathcal{X}=\mathbb{R}^{1}$ denote the unknown (scalar) speed, we have $m$ measurements $y_{i} \sim x$. Let $y \in \mathcal{Y}=\mathbb{R}^{m}$ denote the vector of $m$ measurements and the $m \times 1$ matrix $A$ be the (column) matrix whose values are all 1's. Obviously the dimension of the domain $\mathcal{X}$ is 1 and the dimension of the codomain $\mathcal{Y}$ is $m$. The inverse problem is to solve $y \approx A x$ for $y, A$, and $x$ as defined. The rank of $A$ is 1 , which is the dimension of the range of $A$ and the dimension of the range of $A^{T}$. The nullity (the dimension of the nullspace) is 0 , and the dimension of the left-nullspace, $\mathcal{N}\left(A^{T}\right)$, is $m-1$. The inner product on $\mathcal{Y}$ is $\left\langle y, y^{\prime}\right\rangle=$ $y^{T} y^{\prime}=y_{1} y_{1}^{\prime}+\cdots y_{m} y_{m}^{\prime}$ and the inner product on $\mathcal{X}$ is $\left\langle x, x^{\prime}\right\rangle=x x^{\prime}$. The problem is ill-posed because $A$ is not onto, so that in general the system does not have a true solution. (However $A$ is a full rank matrix since it is one-to-one.) Note that we have assumed that the domain and codomain are cartesian, $\Omega=$ 1 and $W=I$.
(c) i) Construct the adjoint operator of $A$. ii) Construct the pseudoinverse of $A$. Because the spaces are real and cartesian, $A^{*}=A^{T}=(1, \cdots, 1)$. Because $A$ is one-to-one, we have $A^{+}=\left(A^{T} A\right)^{-1} A^{T}=\frac{1}{m}(1, \cdots, 1)$.
(d) Determine the least-squares estimate of the unknown speed. Write the answer in terms of the individual measurements $y_{i}$.

$$
\hat{x}=A^{+} y=\frac{1}{m}\left(y_{1}+\cdots+y_{m}\right)=\text { sample average of the measurements. }
$$

3. (25pts) In $\mathbb{R}^{n}$, the general equation of a hyperplane (a translated subspace of dimension $n-1$ ) is given by

$$
\omega_{1} x_{1}+\cdots+\omega_{n} x_{n}-b=\omega^{T} x-b=0,
$$

for $x \in \mathbb{R}^{n}$. What is the minimum distance of the hyperplane from the origin?
Solve the problem $\min _{x}\|x\|^{2}$ subject to $A x=y$ with $A=\omega^{T}$ and $y=b$ to obtain the vector $x$ from the origin to the hyperplane of shortest length. Since $A$ is (obviously) onto, the solution is given by

$$
x=A^{+} y=A^{T}\left(A A^{T}\right)^{-1} y=\omega \cdot \frac{1}{\omega^{T} \omega} \cdot b=\frac{\omega}{\|\omega\|^{2}} b .
$$

The minimum distance to the hyperplane is given by the magnitude of this vector,

$$
\|x\|=\frac{|b|}{\|\omega\|}=\frac{|b|}{\sqrt{\omega_{1}^{2}+\cdots+\omega_{n}^{2}}}
$$

